

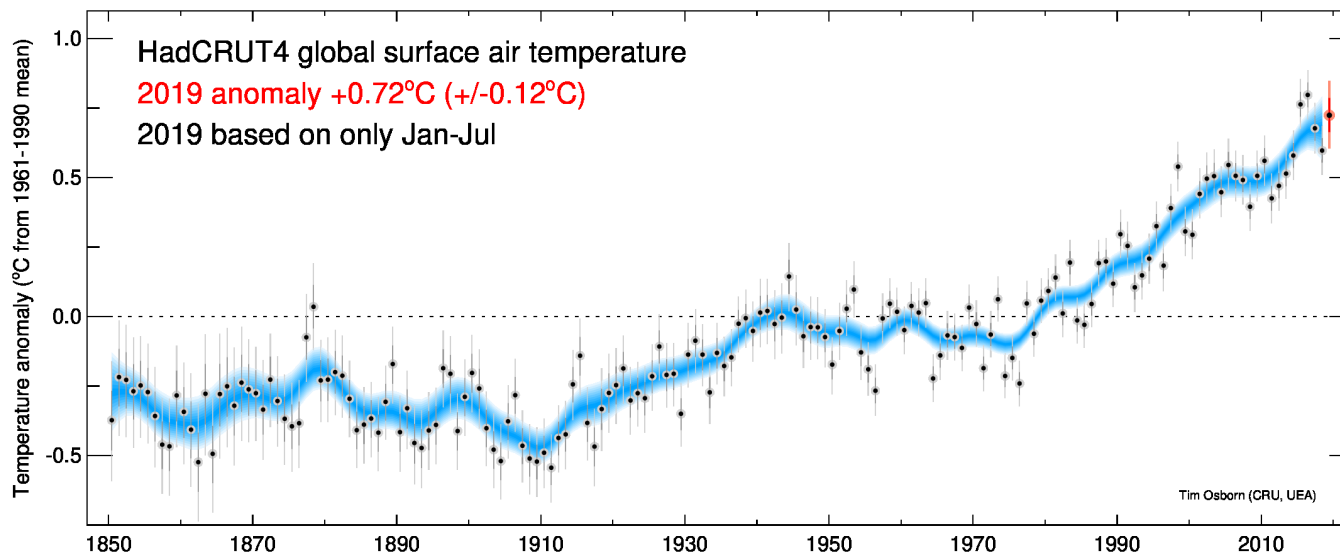
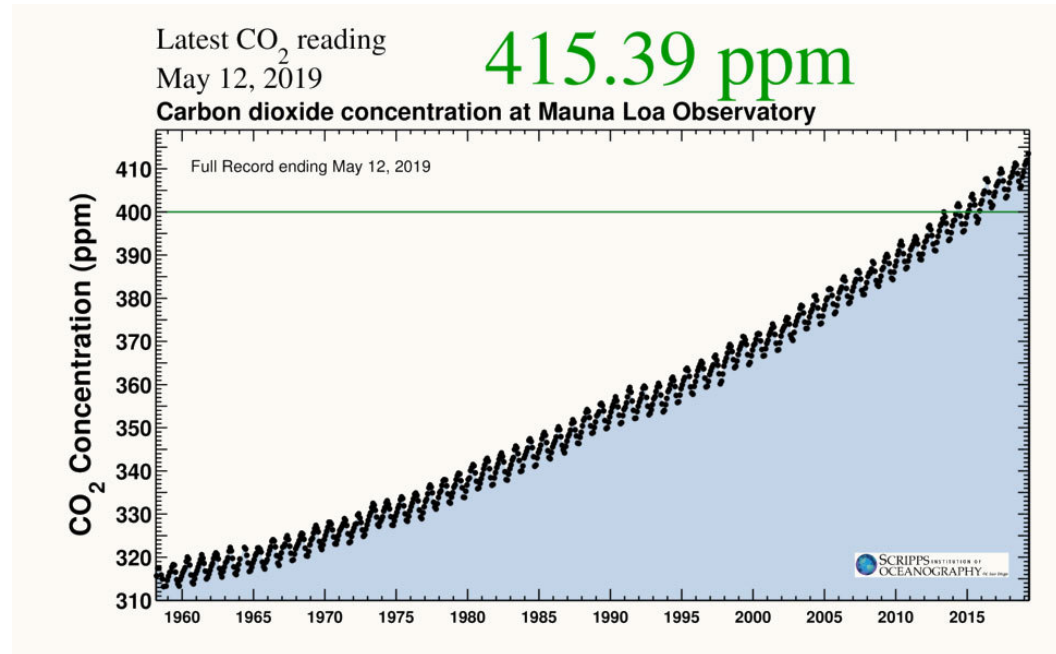
# Applications of linear response theory in climate change research



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# Climate Change: observations



# Main questions?

How warm is it going to be in 2100?

Climate Sensitivity

Are the changes going to be 'smooth' or 'bumpy'?

Tipping Points

When is it too late to act to prevent dangerous climate change through emission reductions?

Safe Carbon Budget, Point of No Return

Are there any alternatives to avoid dangerous climate change?

Negative emissions, Geoengineering

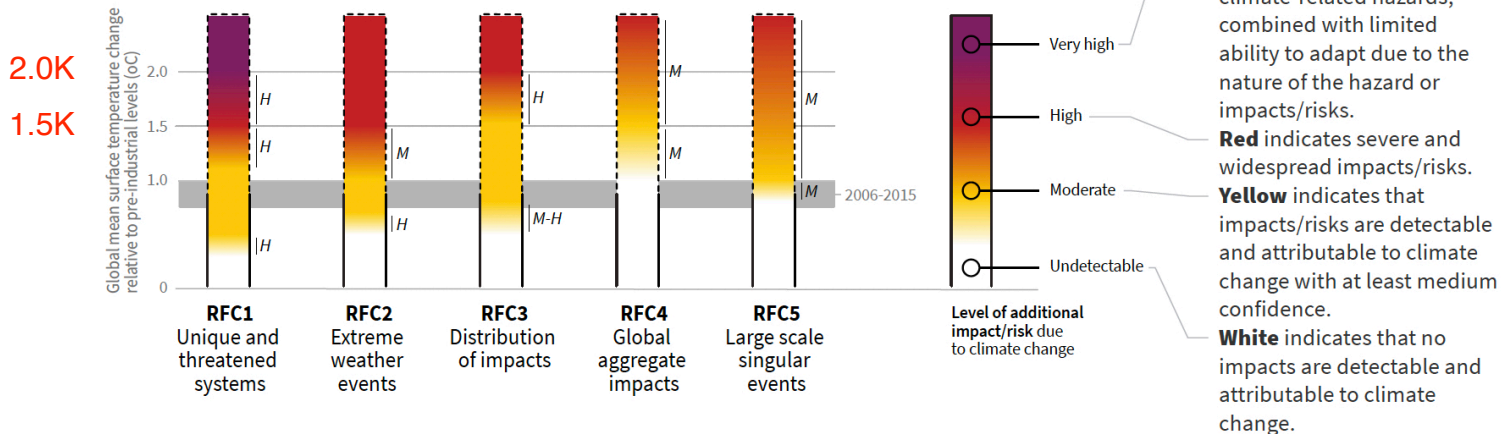
# Dangerous Climate Change?

IPCC SR1.5

## How the level of global warming affects impacts and/or risks associated with the Reasons for Concern (RFCs) and selected natural, managed and human systems

Five Reasons For Concern (RFCs) illustrate the impacts and risks of different levels of global warming for people, economies and ecosystems across sectors and regions.

### Impacts and risks associated with the Reasons for Concern (RFCs)



IPCC, Special Report, October 2018

# Tools

- Coordinated multi-model experiments with GCMs
- “CMIP5 provides a framework for coordinated climate change experimentation” (Taylor, Stouffer, and Meehl, 2012)
- More than 20 modeling groups
- More than 50 models
- Different design ideas, formulations, parameterizations
- Ensemble of “climate realizations”

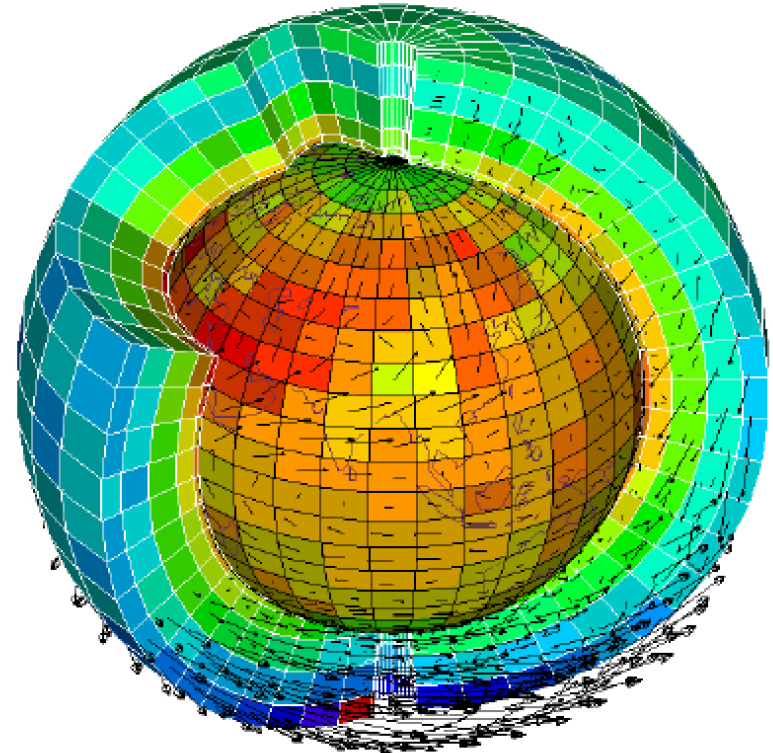
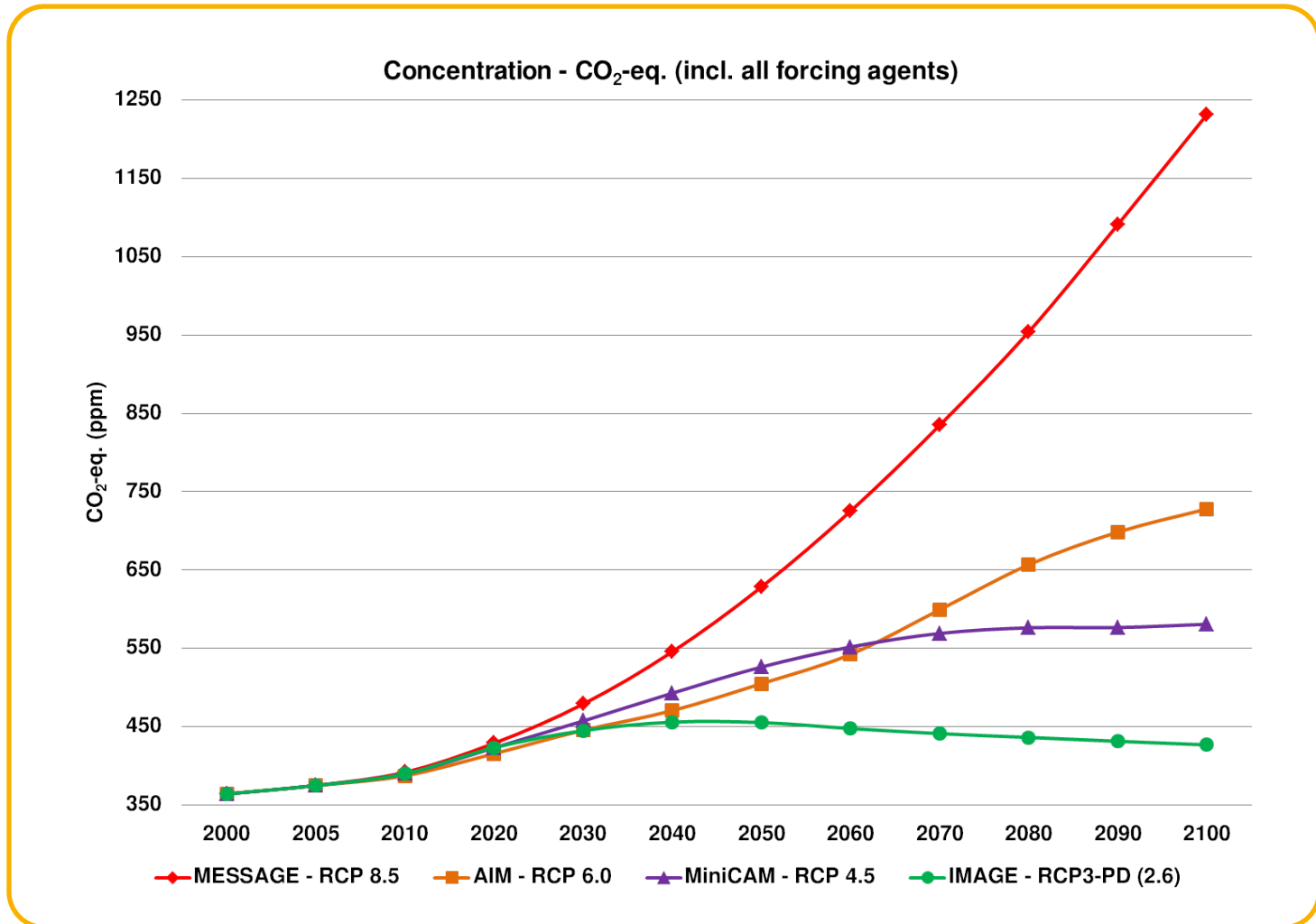
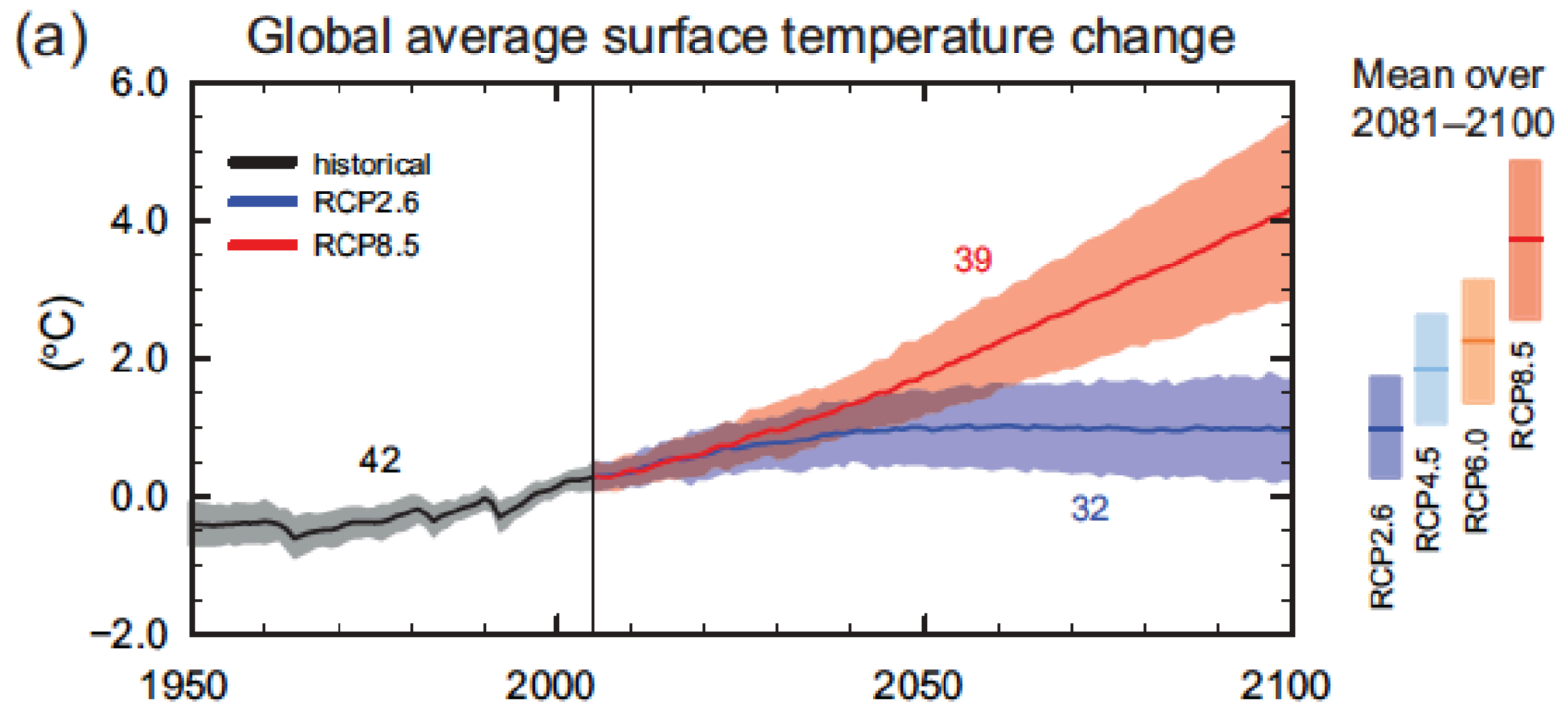


Figure: Global Climate Model  
(Thual, 2013)

# Future Climate Change: Representative concentration pathways



# Projection results



# How to avoid dangerous climate change?

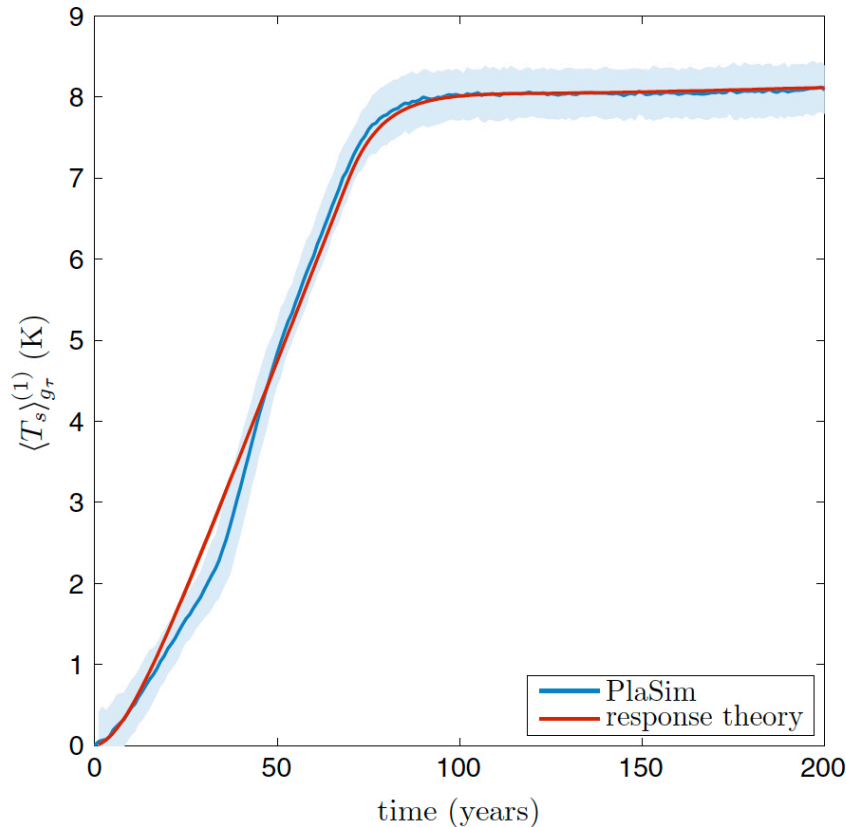
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- Determining what happens under different scenario's
- Evaluate effects of action choices
  - Include uncertainty

Need for an efficient (stochastic) climate (incl. carbon cycle) model !



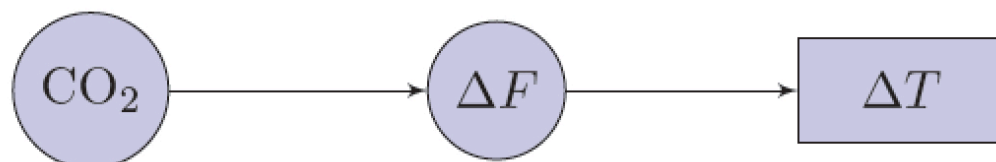
# Linear Response Theory (LRT)



Ruelle (1998)  
Ragone et al, (2016)  
Lucarini et al. (2017)

Using LRT one can determine the response to any forcing!

# Procedure



- Perturbation theory

$$\Delta T_{\Delta F}(t) = \Delta T_0 + \sum_{n=1}^{\infty} \Delta T_{\Delta F}^{(n)}(t) \quad (1)$$

- Linear Response Theory: stop series at  $n = 1$

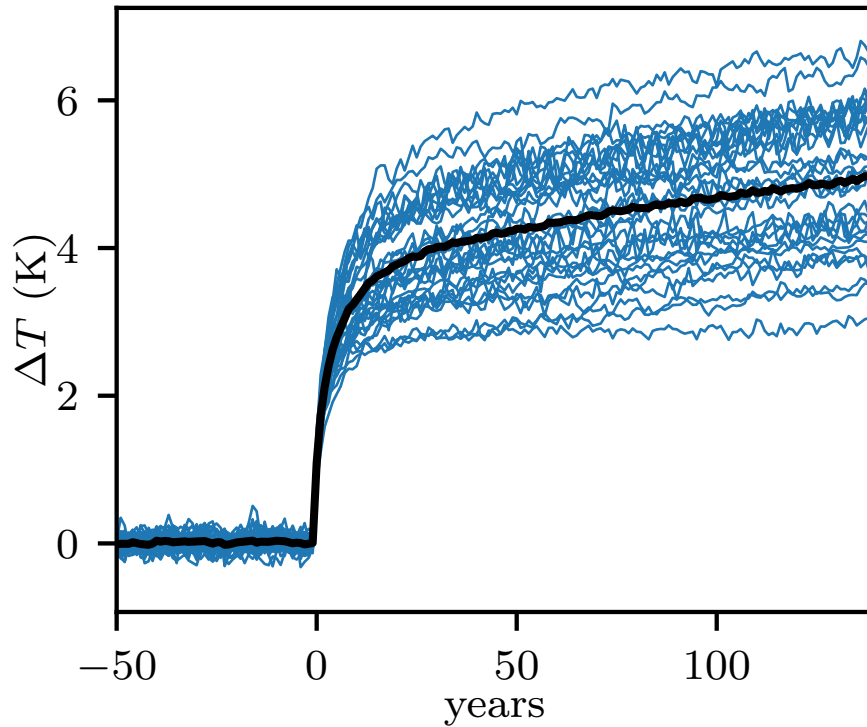
$$\Delta T_{\Delta F}^{(1)}(t) = \int_0^t G_T(t') \Delta F(t - t') dt' \quad (2)$$

- Take a forcing-response pair  $\Delta F_{abrupt}(t) = A\theta(t), \Delta T_{abrupt}(t)$

$$G_T(t) = \frac{1}{A} \frac{d}{dt} \Delta T_{abrupt} \quad (3)$$

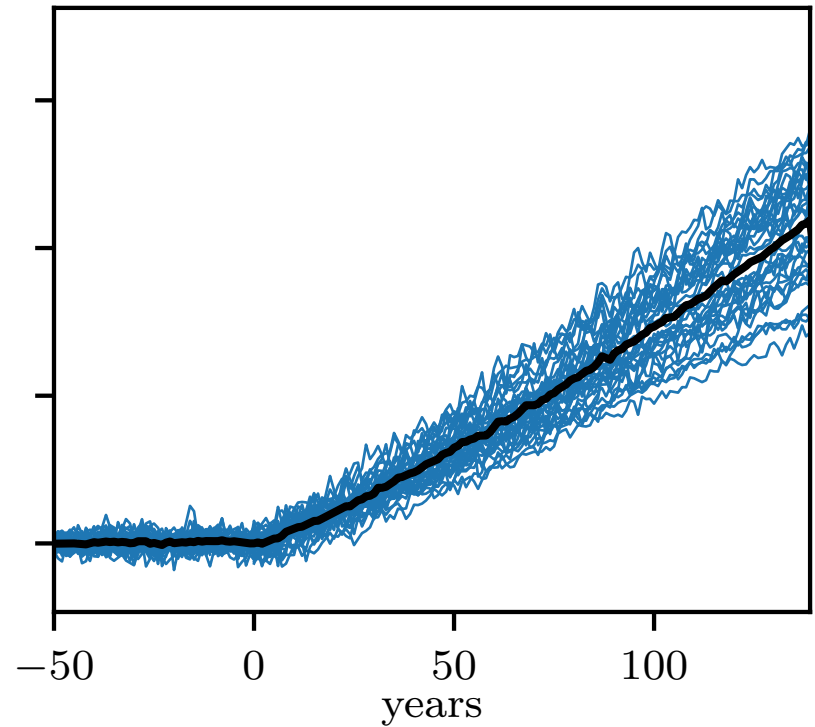
# CMIP5 simulations

Abrupt:  $C_{CO_2}(t) = C_0(3\theta(t) + 1)$



Abrupt forcing

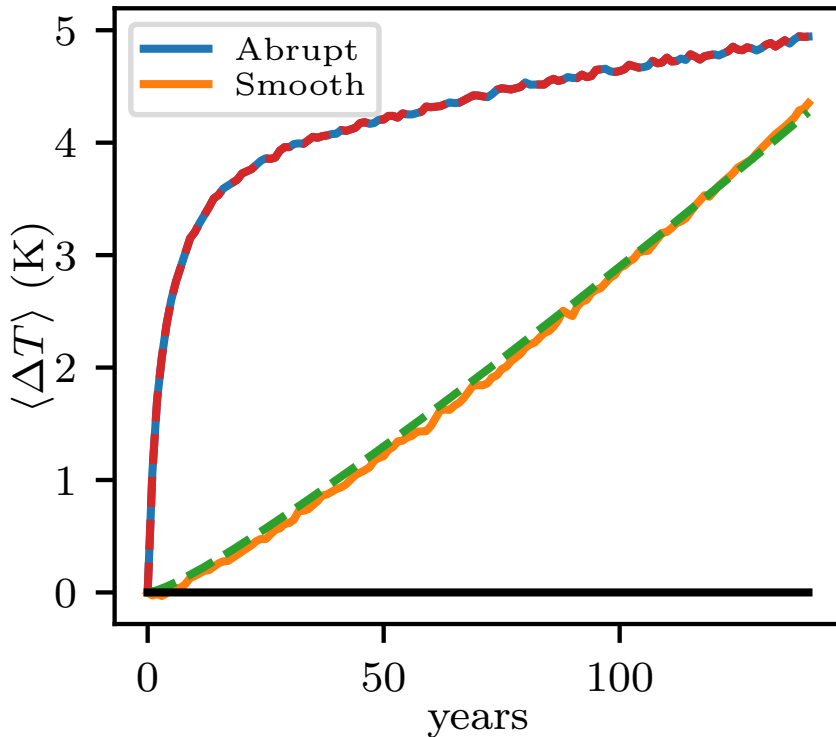
Smooth:  $C_{CO_2}(t) = C_0 1.01^t$



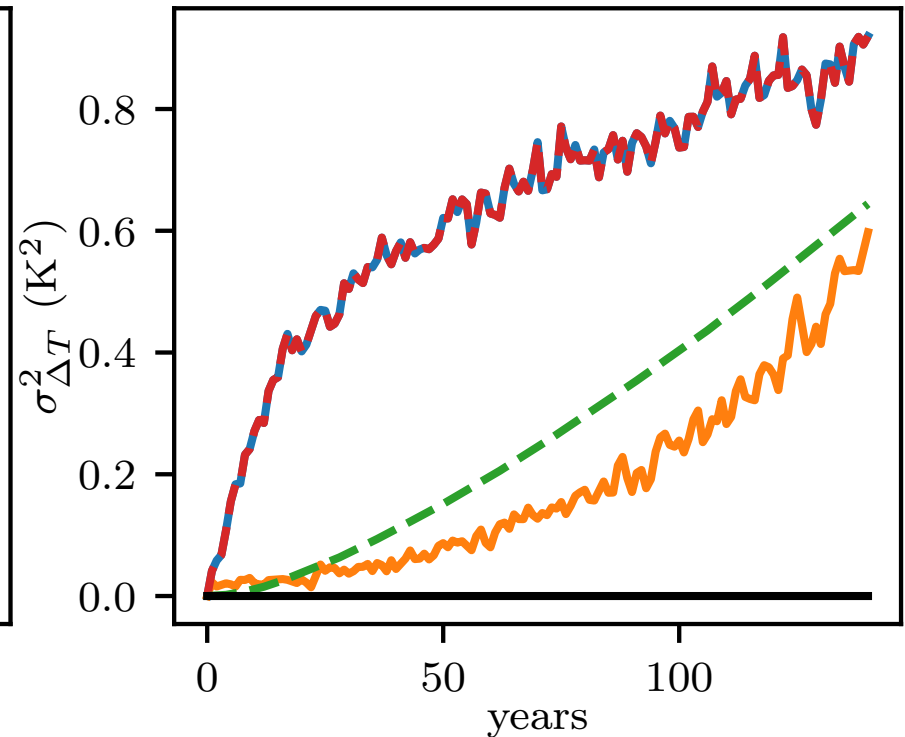
Smooth forcing

# Results Linear Response Theory

Mean



Variance

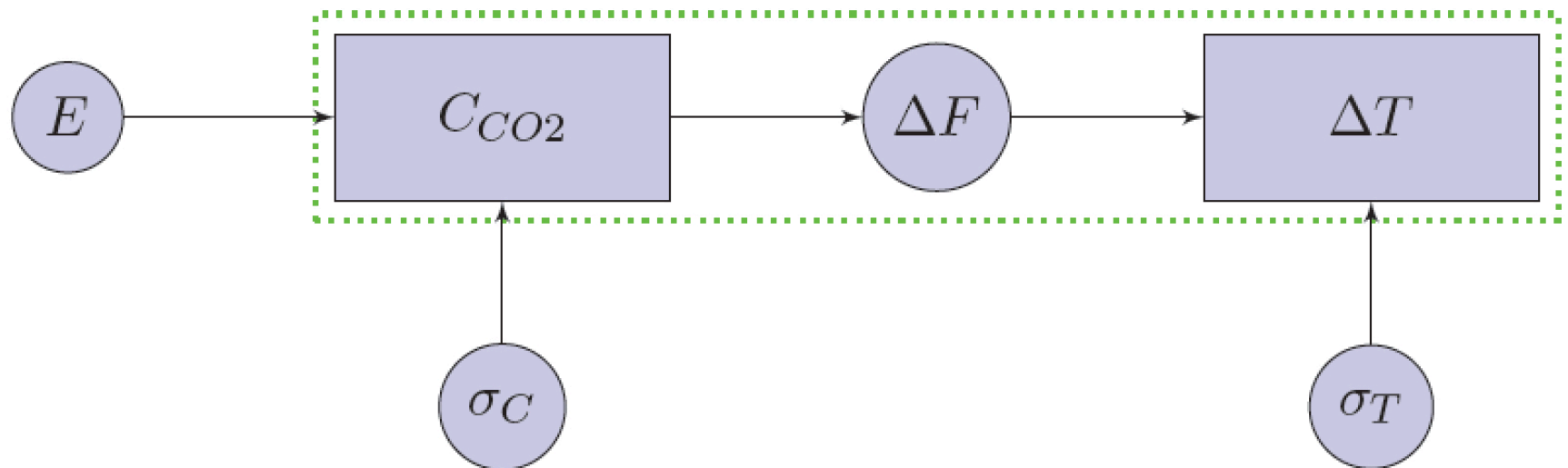


solid: CMIP5

dashed: LRT

# From LRT to Stochastic State Space Model

- Up to now: determine  $\Delta T$  from  $\text{CO}_2$  concentrations
- Climate is forced by *fluxes*
- Relate  $\text{CO}_2$  emissions to concentrations
- Risk, uncertainty: introduce stochasticity



# Coupling a Carbon Model

- Carbon Model (Joos et al., 2013):

$$G_{CO_2}(t) = a_0 + \sum_{i=1}^3 a_i e^{-\frac{t}{\tau_i}} \quad (4)$$

- Full Reponse Function Model

$$C_{CO_2}(t) = C_{CO_2,0} + \int_0^t G_{CO_2}(\tau) E_{CO_2}(t - \tau) d\tau \quad (5)$$

$$\Delta F_{CO_2} = A \alpha_{CO_2} \ln(C/C_0) \quad (6)$$

$$\Delta T(t) = \int_0^t G_T(\tau) \Delta F_{CO_2}(t - \tau) d\tau \quad (7)$$

- We also find:

$$G_T(t) = \sum_{i=0}^2 b_i e^{-t/\tau_{bi}} \quad (8)$$

# Stochastic State Space Model

## Carbon

$$dC_P = a_0 E dt$$

$$dC_1 = \left( a_1 E - \frac{1}{\tau_1} C_1 \right) dt$$

$$dC_2 = \left( a_2 E - \frac{1}{\tau_2} C_2 \right) dt \\ + \sigma_{C_2} dW_t$$

$$dC_3 = \left( a_3 E - \frac{1}{\tau_3} C_3 \right) dt$$

$$C_{CO_2} = C_P + \sum_{i=1}^3 C_i$$

## Temperature

$$\Delta F = A \alpha \ln(C_{CO_2}/C_0)$$

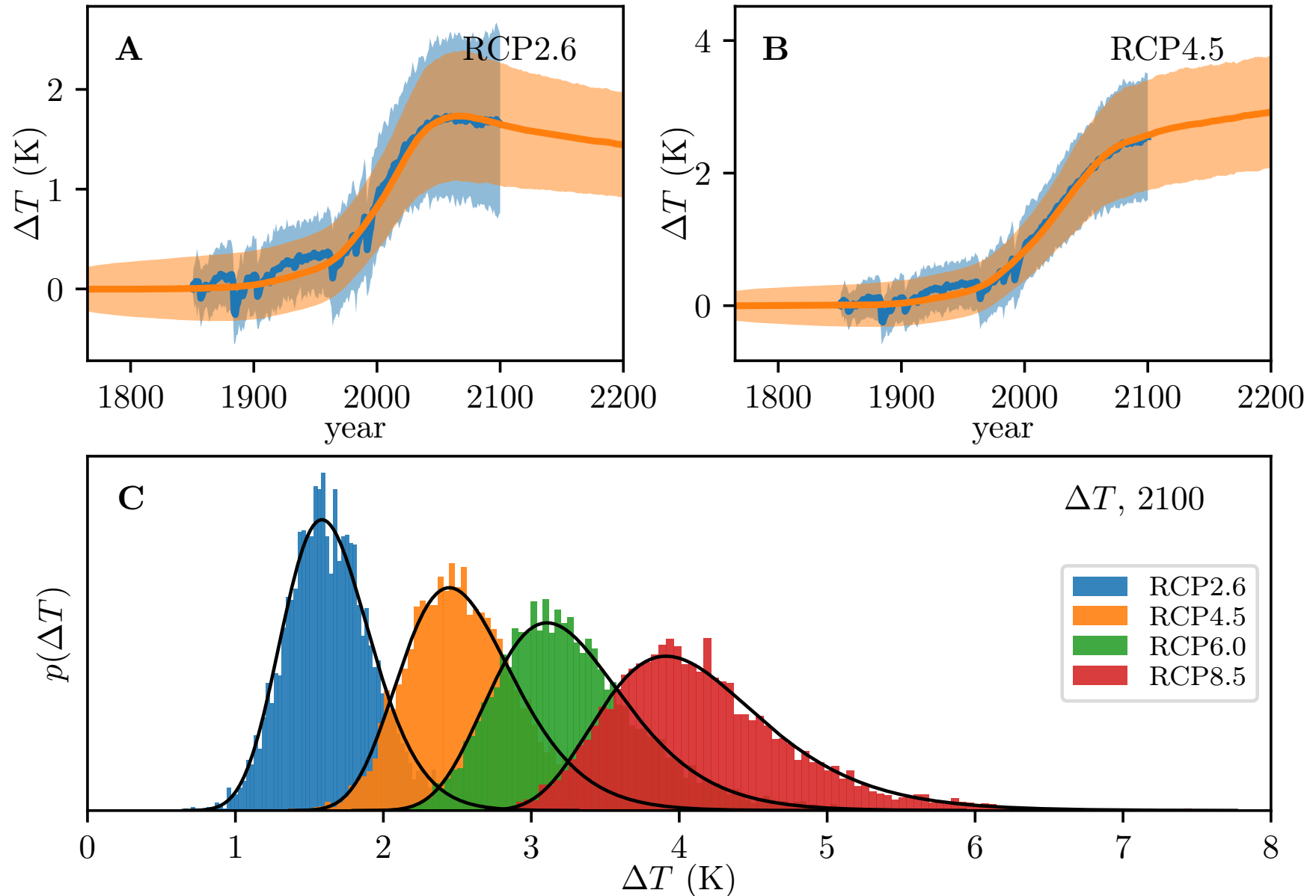
$$d\Delta T_0 = \left( b_0 \Delta F - \frac{1}{\tau_{b0}} \Delta T_0 \right) dt \\ + \sigma_{T_0} dW_t$$

$$d\Delta T_1 = \left( b_1 \Delta F - \frac{1}{\tau_{b1}} \Delta T_1 \right) dt$$

$$d\Delta T_2 = \left( b_2 \Delta F - \frac{1}{\tau_{b2}} \Delta T_2 \right) dt \\ + \sigma_{T_2} \Delta T_2 dW_t$$

$$\Delta T = \sum_{i=0}^2 \Delta T_i$$

# Results: Probability density functions



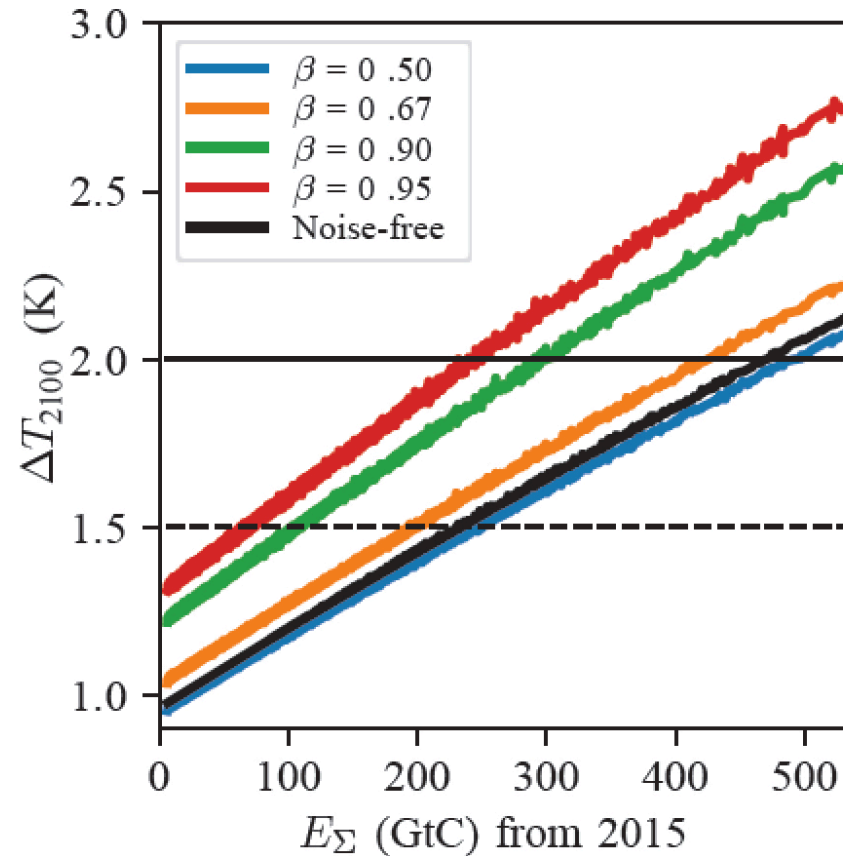


# Save Carbon Budget

Maximum Cumulative Emissions that reach a certain warming target

$$p(\Delta T \leq T_{max}) = \beta$$

$$T_{max} = \Delta T_{2100}$$



**Table 3.** Safe Carbon Budget (in GtC since 2015) as a function of threshold and safety probability  $\beta$ .

$\beta$	0.5	0.67	0.9	0.95	Noise-free
$T_{max} = 1.5$ K	247	198	107	69	233
$T_{max} = 2$ K	492	424	298	245	469

IPCC-AR5: 377 - 517 GtC to likely stay below 2 K  
 Millar et al. (2017): 200 GtC to likely stay below 1.5 K

# Economy & Transition pathways

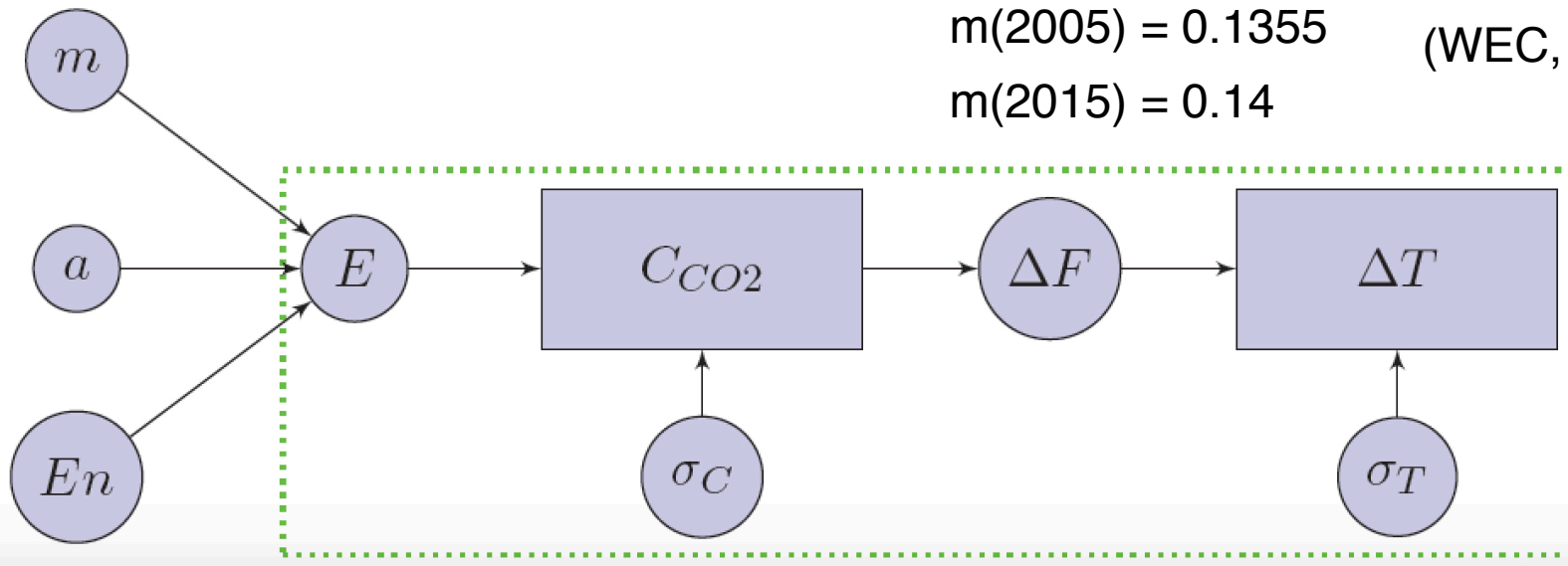
$$Y = Y_0 e^{gt}$$

$$En = \gamma_0 e^{-r_\gamma t} Y$$

$$E = (1 - a)(1 - m)En$$

- 1 Extreme Mitigation (EM): From time  $t_a$  on, we set  $m = 1$ , i.e.  $E = 0$ .
- 2 Fast Mitigation (FM): From time  $t_a$  on, both  $a, m$  increase by 0.05 per year.
- 3 Ambitious Mitigation (AM): As FM, but the increase is 0.02 per year.

$m(2005) = 0.1355$  (WEC, 2016)  
 $m(2015) = 0.14$



# Point of No Return (PONR)

- Use economical assumptions to determine emissions  
⇒ baseline ‘business-as-usual’ scenario
- Control emissions by mitigation  $m(t)$  and abatement  $a(t)$  ⇒  
actions on climate change modify ‘business-as-usual’ scenario

## Definition (Point of No Return)

*The Point of No Return (PONR) is the time  $t_P$  from which on no allowed  $[a(t), m(t)]$  such that  $0 \leq a(t), m(t) \leq 1, t_P \leq t \leq t_f$  can be chosen to fulfill*

$$p(\Delta T(t_f) \leq T_{max}) \geq \beta$$

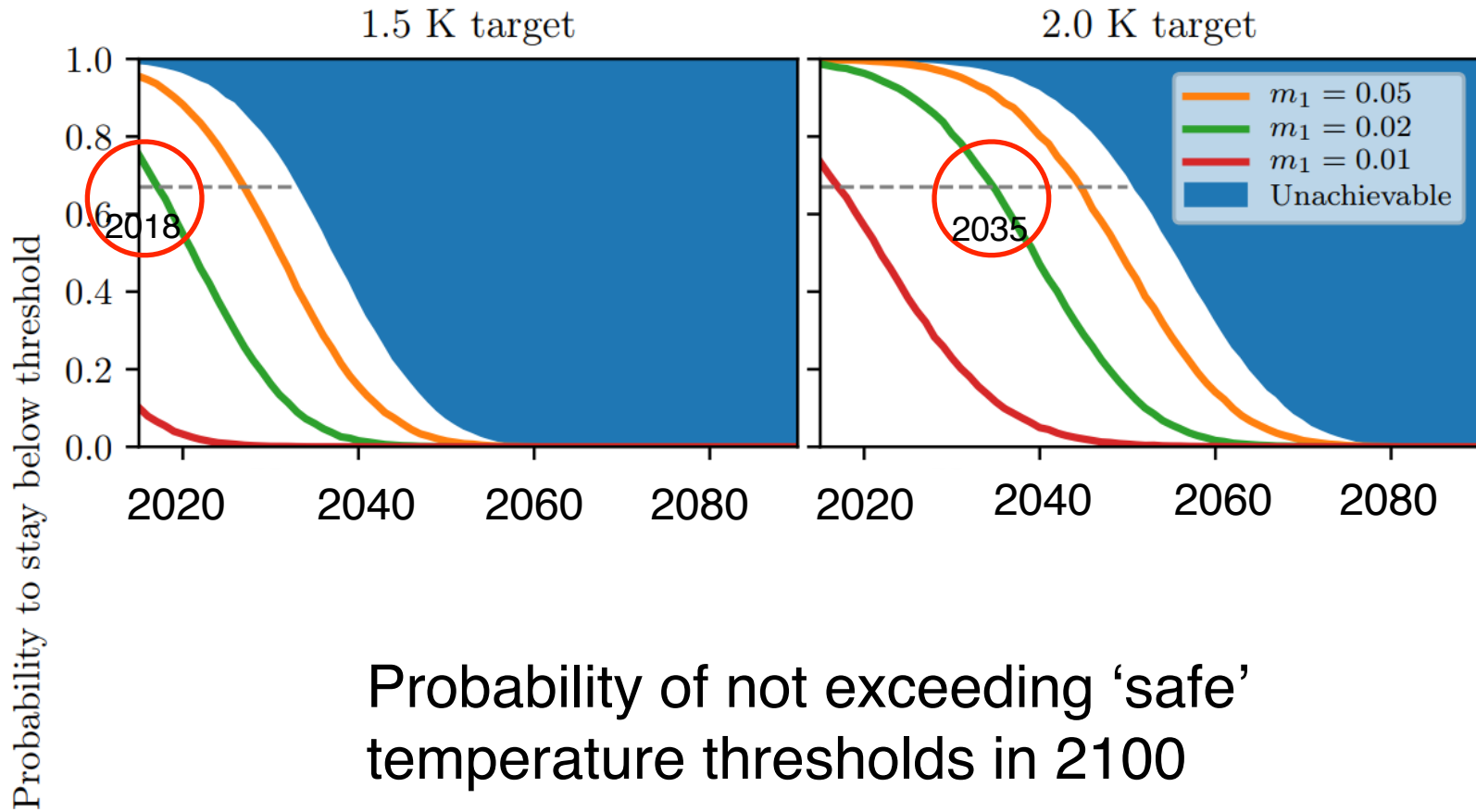
**Save Carbon Budget:**

**We cannot reach target X by emitting more than Y**

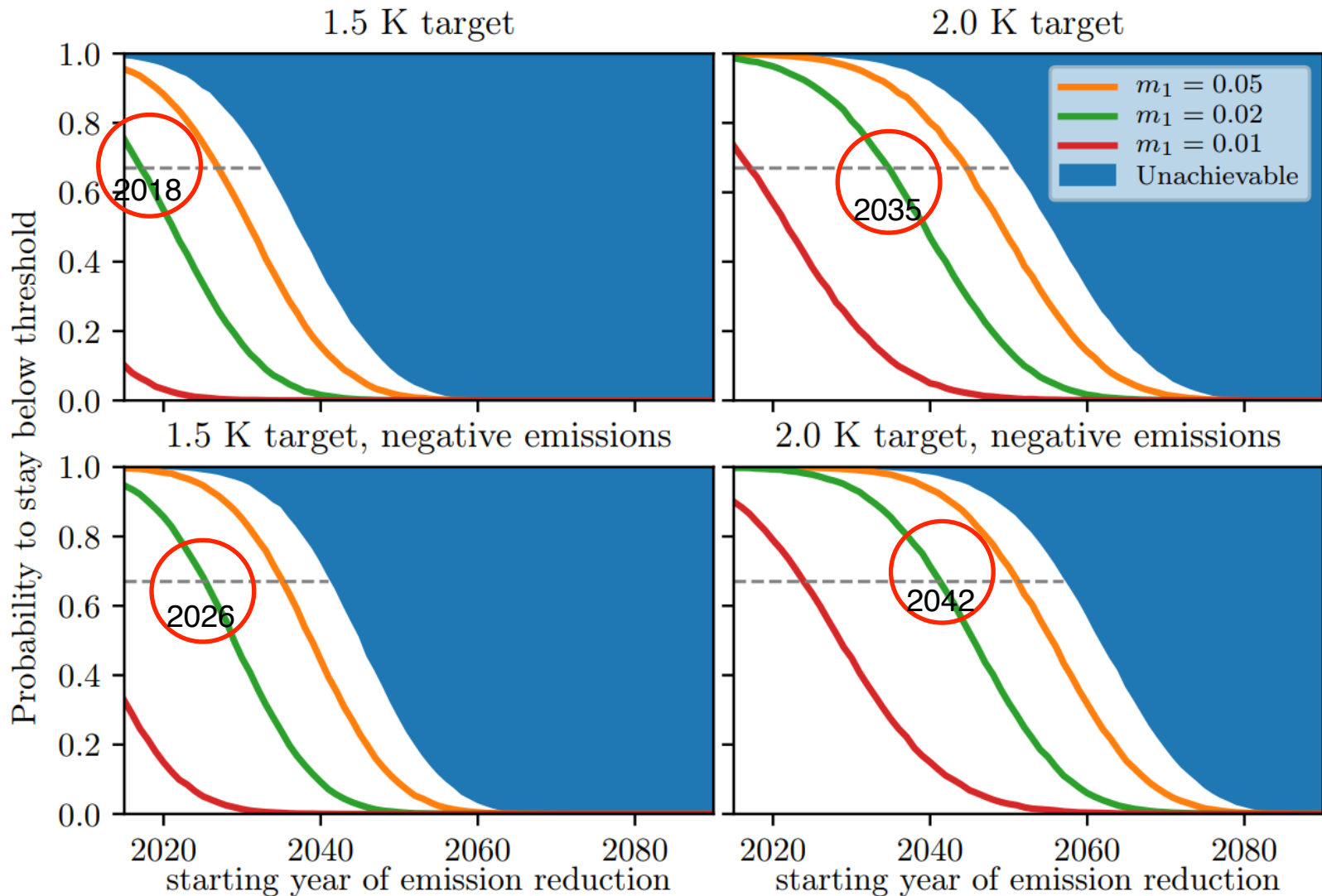
**Point of No Return:**

**We cannot reach target X by starting reduction after year T**

# PONR: results



# Effect of Negative Emissions



Probability of not exceeding 'safe' temperature thresholds in 2100

# PONR: results

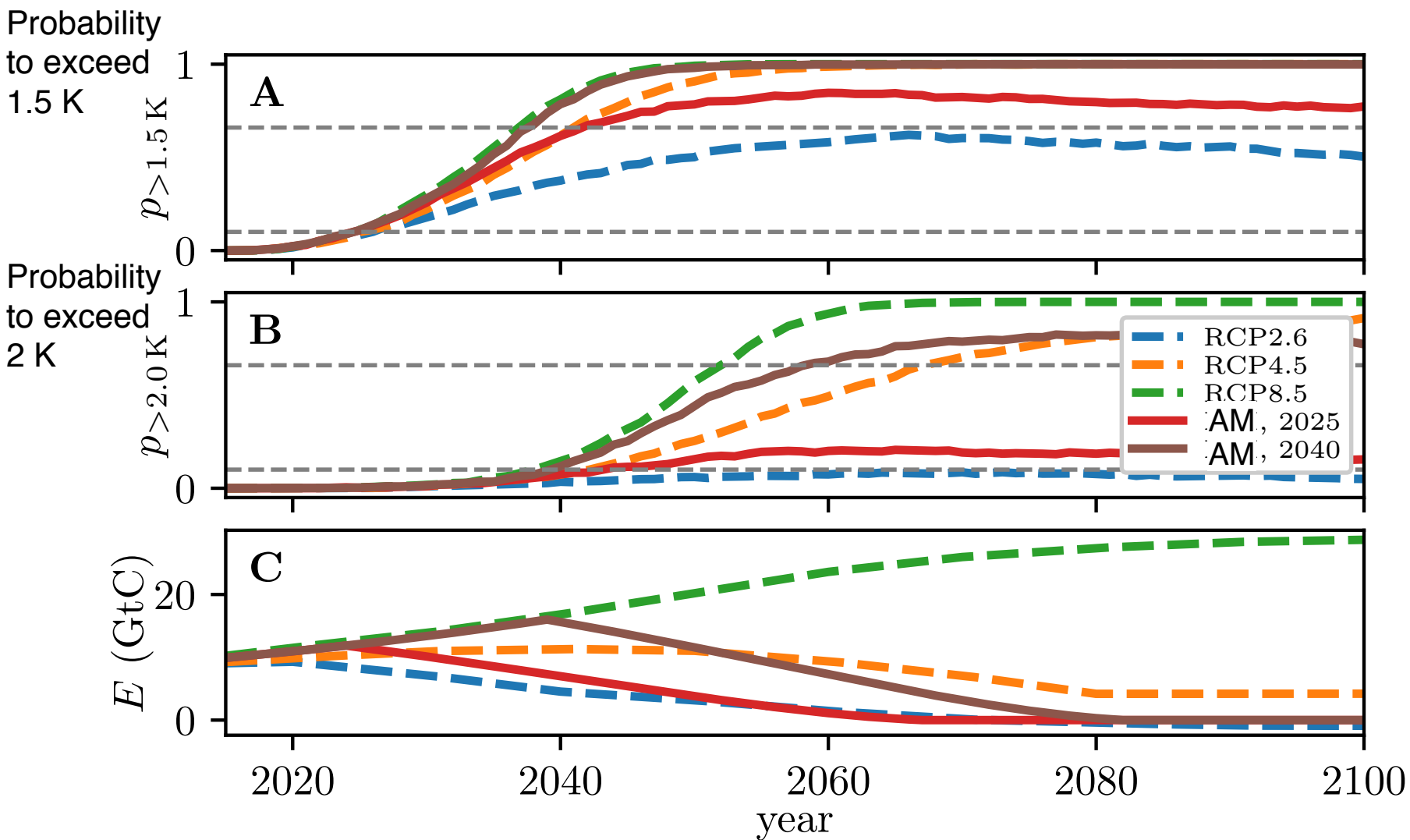
- ① Extreme Mitigation (EM): At time  $t_a$ , we set  $m = 1$ , so  $E = 0$  from then onward.
- ② Fast Mitigation (FM): From time  $t_a$  onwards, both  $a, m$  increase by 0.05 per year.
- ③ Ambitious Mitigation (AM): As FM, but the increase is 0.02 per year.

**Table 4.** Point of no return as a function of threshold and safety probability  $\beta$  without and with strong negative emissions.

$\beta$		0.5		0.67		0.9		0.95		noise-free	
		none	strong	none	strong	none	strong	none	strong	none	strong
EM	$T_{\max} = 1.5 \text{ K}$	2038	2046	2034	2042	2026	2035	2022	2032	2037	2045
	$T_{\max} = 2 \text{ K}$	2056	2062	2051	2058	2042	2049	2038	2046	2055	2061
FM	$T_{\max} = 1.5 \text{ K}$	2032	2039	2027	2036	2020	2028	2016	2025	2030	2038
	$T_{\max} = 2 \text{ K}$	2050	2056	2045	2052	2036	2043	2032	2039	2048	2055
AM	$T_{\max} = 1.5 \text{ K}$	2022	2029	2018	2026	–	2019	–	–	2021	2029
	$T_{\max} = 2 \text{ K}$	2040	2046	2035	2042	2026	2033	2022	2030	2038	2045

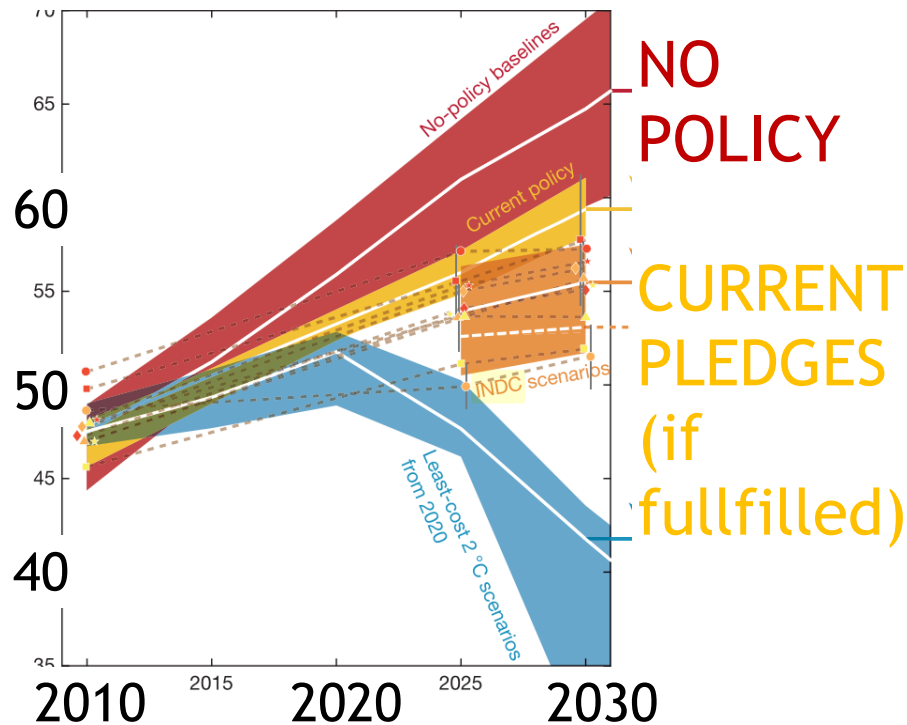
The PNR for 1.5 K has been passed!

# Scenarios



# Current Climate Policy

annual GHG  
emissions  
(Gt(CO<sub>2</sub> eq) /  
year)



Rogelj et al. 2016

NEEDED  
TO REACH  
EVEN 2°C

**Even if all states  
keep their  
intended  
contributions,  
we are NOT  
on the right path  
to reach the  
Paris agreement!**

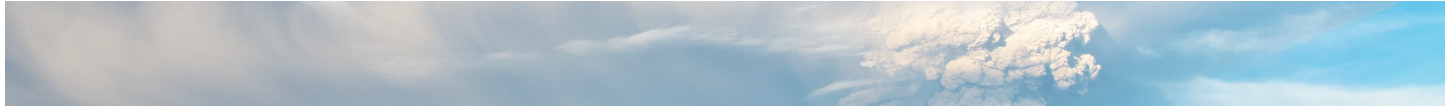


# Summary

- Shown value of Linear Response Theory in the CMIP5 context
- Build an stochastic state space model to adequately determine the climate response to emissions.
- Easy to communicate metrics:
  - SCB: “We cannot reach target X when emitting more than S
  - PONR: “We cannot reach target X when starting after year PONR”

PONR with realistic action pathways is close (2035 for 67%) for the 2K target and already passed for the 1.5K target.

# Further reading



**M. Aengenheyster, Q. Feng, F. van der Ploeg and H. A. Dijkstra.  
The point of no return for climate action: effects of climate  
uncertainty and risk tolerance  
Earth System Dynamics, 9, 1085-1095, (2018)**

**K. Helwegen, C. Wieners, J. Frank and H. A. Dijkstra.  
Complementing CO<sub>2</sub> emission reduction by solar radiation  
management might strongly enhance future welfare, Earth System  
Dynamics, 10, 453-472, (2019).**